

IBM Research

Attributing anomalies from black-box predictions

Tsuyoshi (Ide-san) Ide (井手 剛)

tide@us.ibm.com

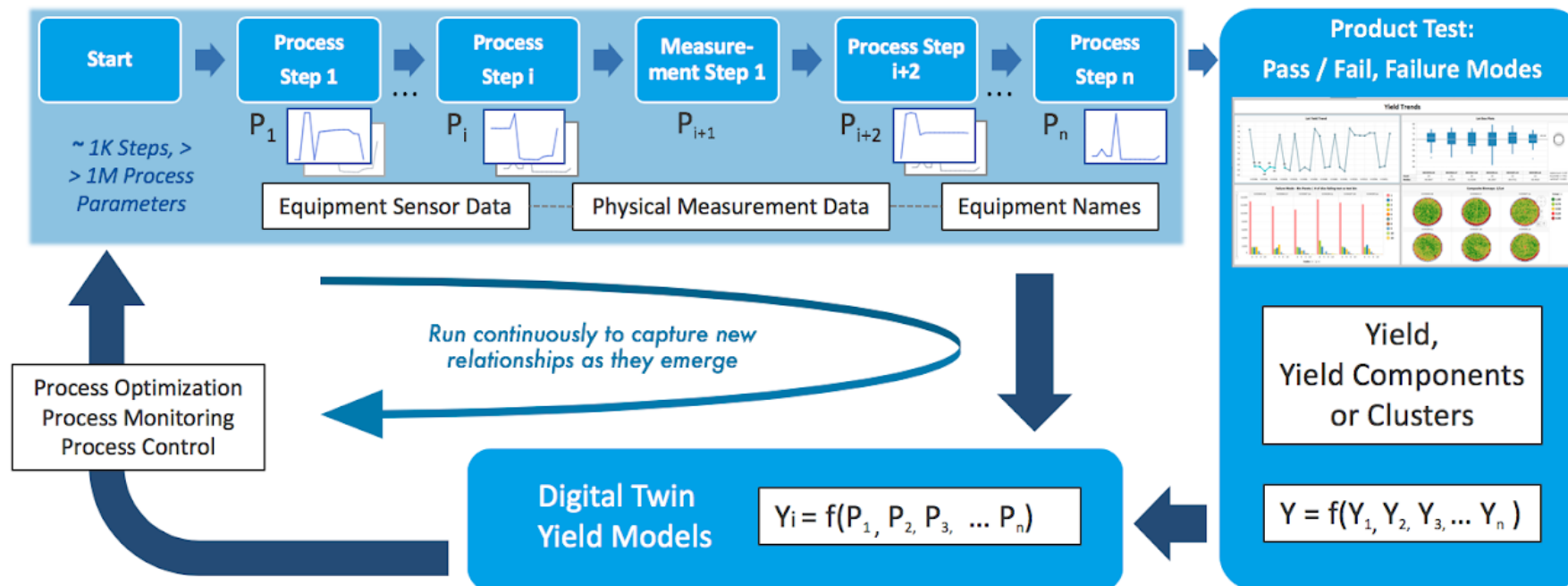
IBM Semiconductors, T. J. Watson Research Center

Agenda

- What is the task, “Anomaly Attribution”?
- What’s wrong with the existing attribution methods?
- What is the new idea?
- Illustrative examples
- Summary

Digital twin is a black-box function to predict a KPI. Explainability is crucial.

- Example: Yield prediction as a function of process parameters.
 - Mfg. process is so complex that data-driven models (e.g., DNN) are used to get $y = f(\cdot)$.



- **Explainability of prediction** is critical for process improvement

“Anomaly attribution” addresses the key question of digital twins

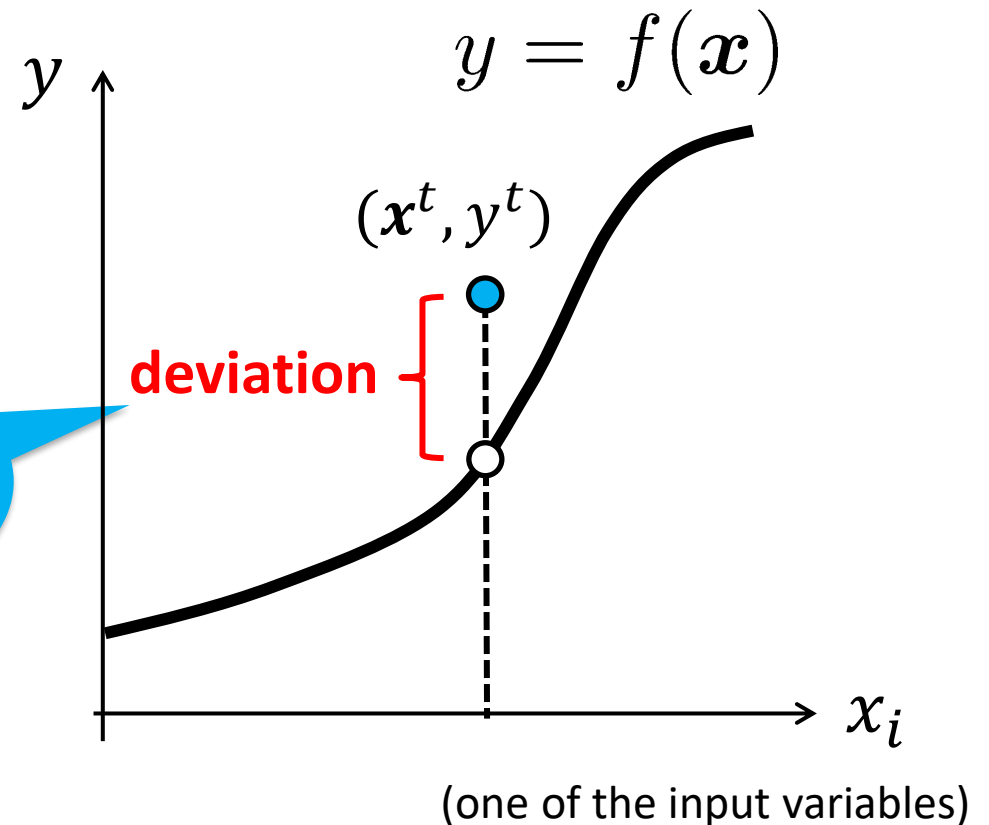
Given:

- Black-box regression model $y = f(x)$ and a (set of) test sample (x^t, y^t)
 - No access to the model beyond API
 - No access to the training data

Explain:

- The deviation $f(x^t) - y^t$
- by computing the attribution score (responsibility score) for *each* of the input variables x .

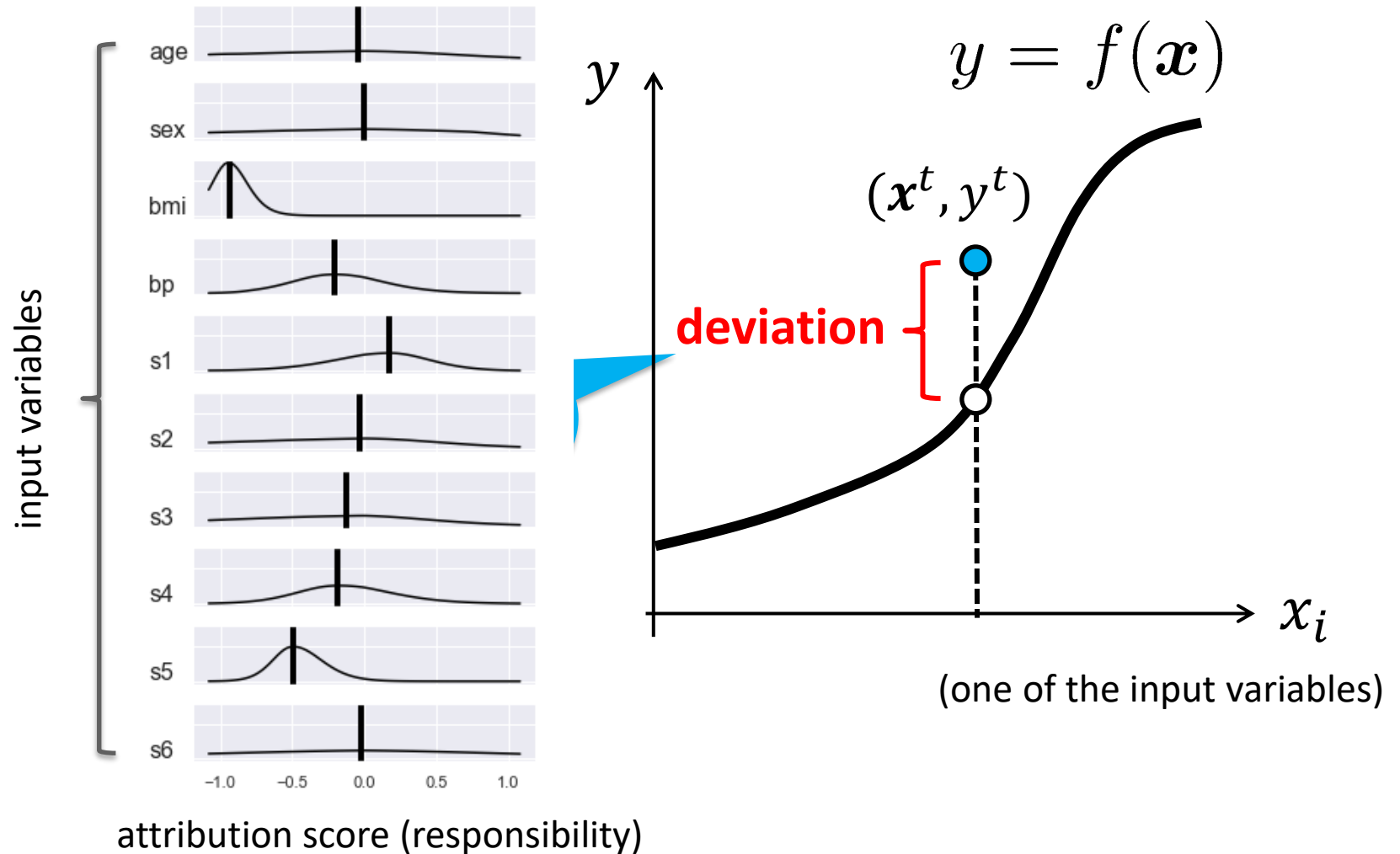
Why did I get this?



Seeking an automated way of computing the responsibility of an observed anomaly

Practical requirements of anomaly attribution

- Able to explain the deviation (Sounds obvious, huh?)
- Able to compute the uncertainty of the score (challenging)



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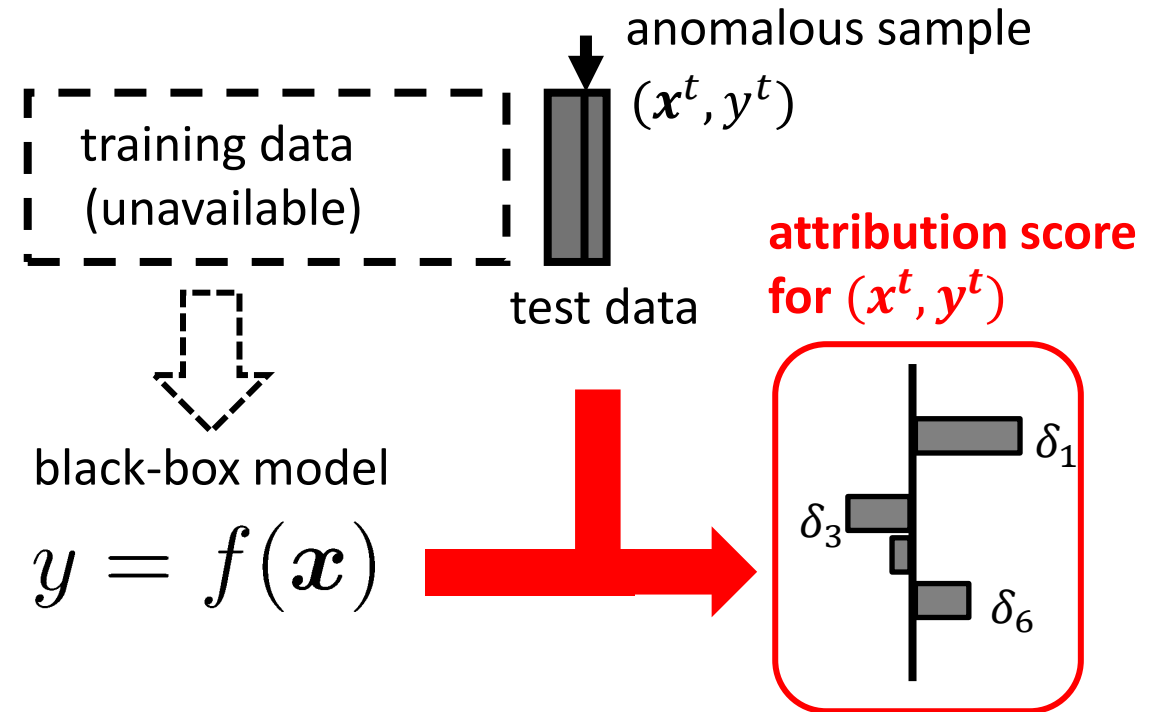
LIME, Shapley values (SV), and integrated gradient (IG) are three major existing black-box attribution methods.

- LIME, SV, IG are well-established model-agnostic attribution methods
 - In: black-box $y = f(\mathbf{x})$ and test sample.
 - Out: attribution score for each variable

- Why bother to develop a new method?

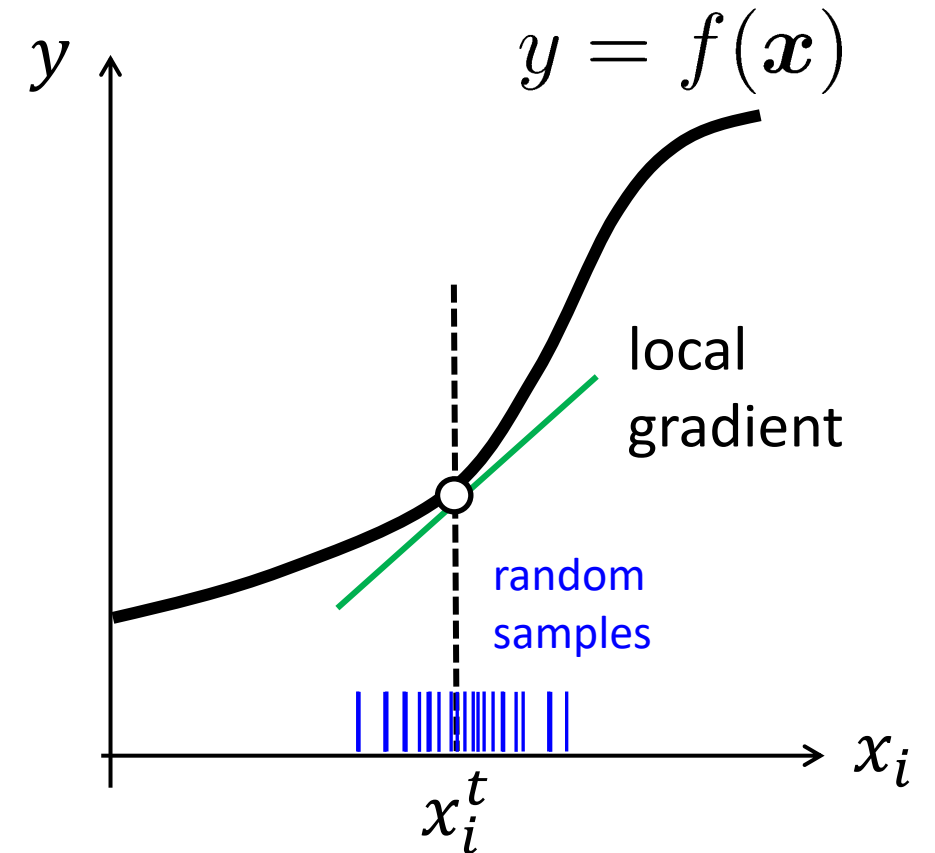
They are, in fact, deviation-agnostic.

They can't compute score's uncertainty



(For ref.) LIME [Ribeiro+ 16] does local sensitivity analysis of the black-box function

- Sensitivity = gradient = attribution score
- Challenge:
 - $f(\mathbf{x})$ is black-box; No way of getting the gradient analytically.
- Idea:
 - Randomly generate samples around \mathbf{x}^t
 - ✓ $\{(\mathbf{x}^{t[1]}, y^{t[1]}), \dots, (\mathbf{x}^{t[N]}, y^{t[N]})\}$ where $y^{t[n]} = f(\mathbf{x}^{t[n]})$.
 - Fit a (sparse) linear model (lasso)
 - ✓ $y = \mathbf{a}^\top \mathbf{x} + b$
 - The regression coefficients is an estimator of the gradient (= explanation).



- Ribeiro, Marco Tulio, Sameer Singh, and Carlos Guestrin. "Why should I trust you?: Explaining the predictions of any classifier." Proceedings of the 22nd ACM SIGKDD international conference on knowledge discovery and data mining. ACM (2016).
- LIME: Local Interpretable Model-agnostic Explanations

(For ref.) Integrated gradient (IG) computes the increment from a reference point

■ Definition of IG [Sippl 20]

- Increment from a reference point \mathbf{x}^0

$$\text{IG}_i(\mathbf{x}^t | \mathbf{x}^0) \triangleq (x_i^t - x_i^0) \int_0^1 d\alpha \left. \frac{\partial f}{\partial x_i} \right|_{\mathbf{x}^0 + (\mathbf{x}^t - \mathbf{x}^0)\alpha}$$

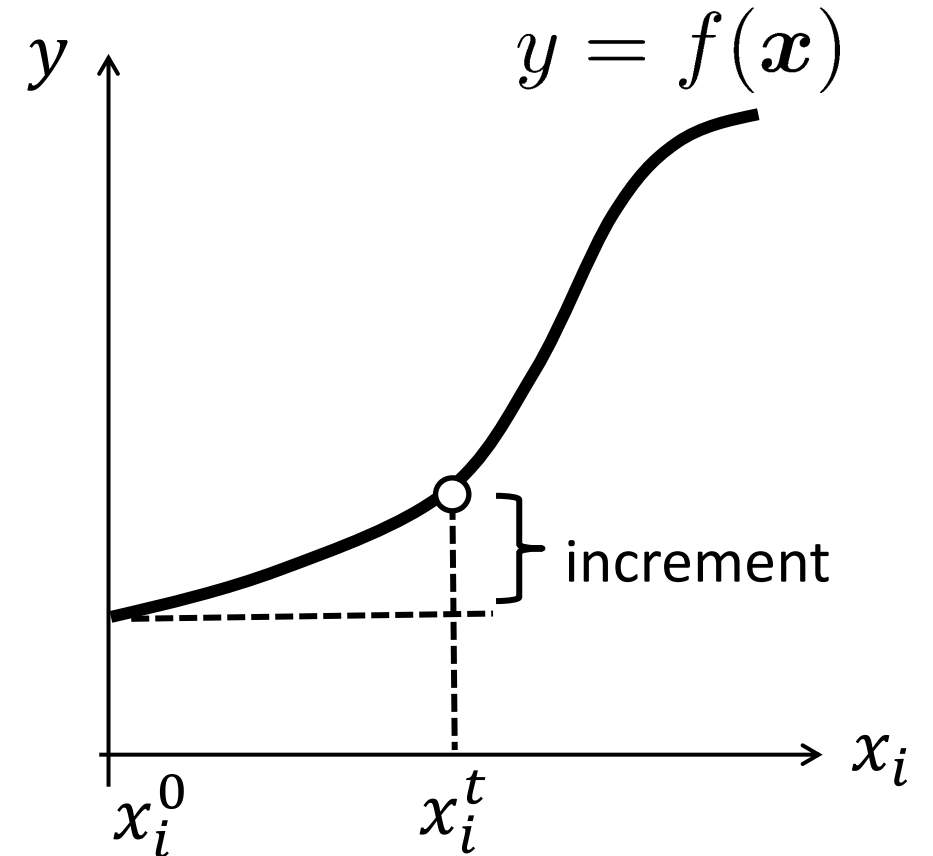
- The gradient is numerically estimated with a LIME-like approach.
- The integral is also evaluated numerically

■ Expected IG (EIG) [Deng+ 21]

- Computed by marginalizing \mathbf{x}^0 with a distribution of the reference point

$$\text{EIG}_i(\mathbf{x}^t | \mathbf{x}^0) \triangleq \int d\mathbf{x}^0 \underbrace{P(\mathbf{x}^0)}_{\text{typically empirical distribution of the training samples}} \text{IG}_i(\mathbf{x}^t | \mathbf{x}^0)$$

typically empirical distribution of the training samples



- John Sippl. “Interpretable, Multidimensional, Multimodal Anomaly Detection with Negative Sampling for Detection of Device Failure,” In Proceedings of the 37th International Conference on Machine Learning (ICML 20).
- Huiqi Deng, et al. , A Unified Taylor Framework for Revisiting Attribution Methods. In Proceedings of the AAAI Conference on Artificial Intelligence. 11462–11469, 2021.

(For ref.) Shapley values (SV) originate from game theory.

- SV originated from game theory and are defined without relying on geometric interpretations.

- The definition is a bit nonintuitive:
$$SV_i(\mathbf{x}^t) = \frac{1}{M} \sum_{k=0}^{M-1} \binom{M-1}{k}^{-1} \sum_{\mathcal{S}_i: |\mathcal{S}_i|=k} \Delta f(x_i^t, \mathcal{S}_i)$$

- \mathcal{S}_i : A variable set (of size k) excluding i .
- If $M = 4, i = 1, k = 2$, and $\mathcal{S}_1 = \{2, 3\}$,

$$\checkmark \Delta f(x_1^t, \mathcal{S}_1) = \frac{1}{N} \sum_{n=1}^N [f(x_1^t, x_2^t, x_3^t, x_4^{(n)}) - f(x_1^{(n)}, x_2^t, x_3^t, x_4^{(n)})]$$

- SV quantifies the impact of the i -th variable by contrasting the expected values when x_i is set to x_i^t , versus when x_i is averaged out.
- SV looks mysterious, but fortunately (and unexpectedly), $SV \approx \text{EIG}$ holds!

Can they explain deviations by changing the target to $f(\mathbf{x}) - y$?

– Actually, no. Summary of theoretical results [Ide-Abe 23].

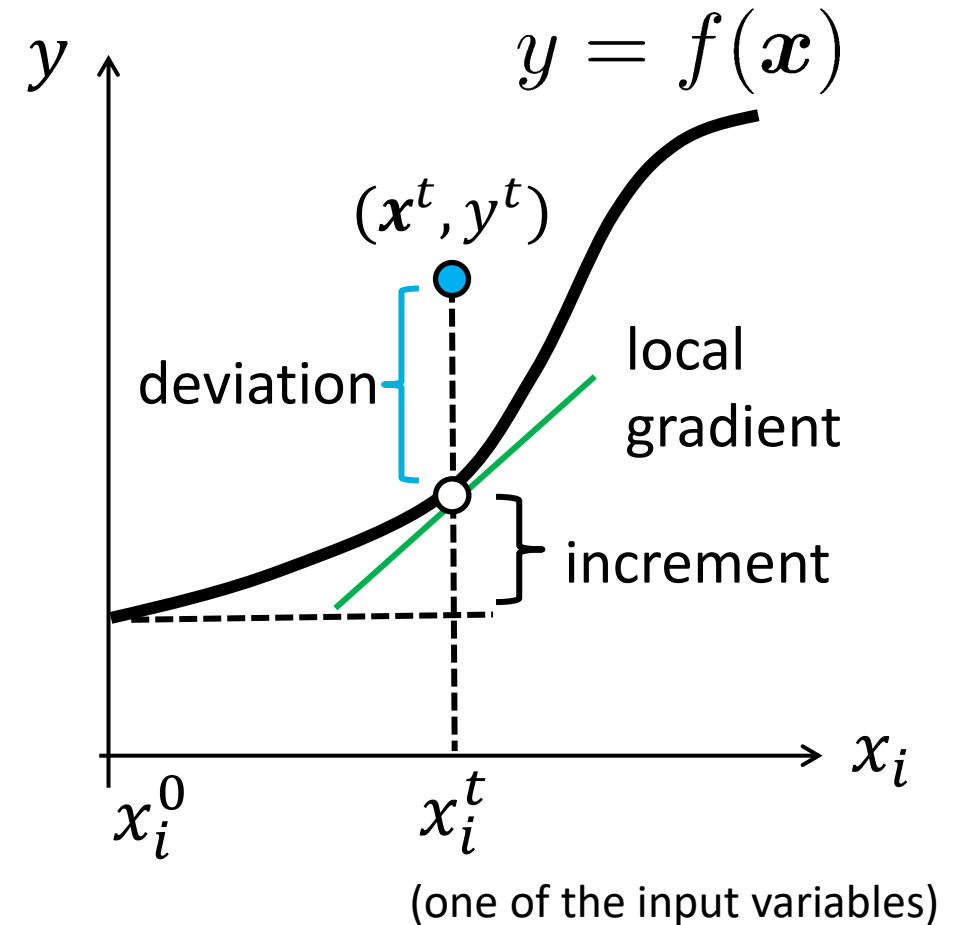
- Result 1: LIME, SV, IG, and EIG are deviation-agnostic
 - This is obvious from the original definition.
 - ✓ They explain $f(\mathbf{x})$ locally at $\mathbf{x} = \mathbf{x}^t$, independently y .
 - The conclusion still holds even when the target function is $f(\mathbf{x}) - y$ rather than $f(\mathbf{x})$.

- Result 2: SV is equivalent to EIG up to the second order of power expansion.

$$SV_i(\mathbf{x}^t, y^t) \approx \text{EIG}_i(\mathbf{x}^t, y^t)$$

- Result 3: LIME is equivalent to the derivative of IG and EIG

$$\text{LIME}_i(\mathbf{x}^t, y^t) = \frac{\partial \text{EIG}_i(\mathbf{x}^t, y^t)}{\partial x_i}$$

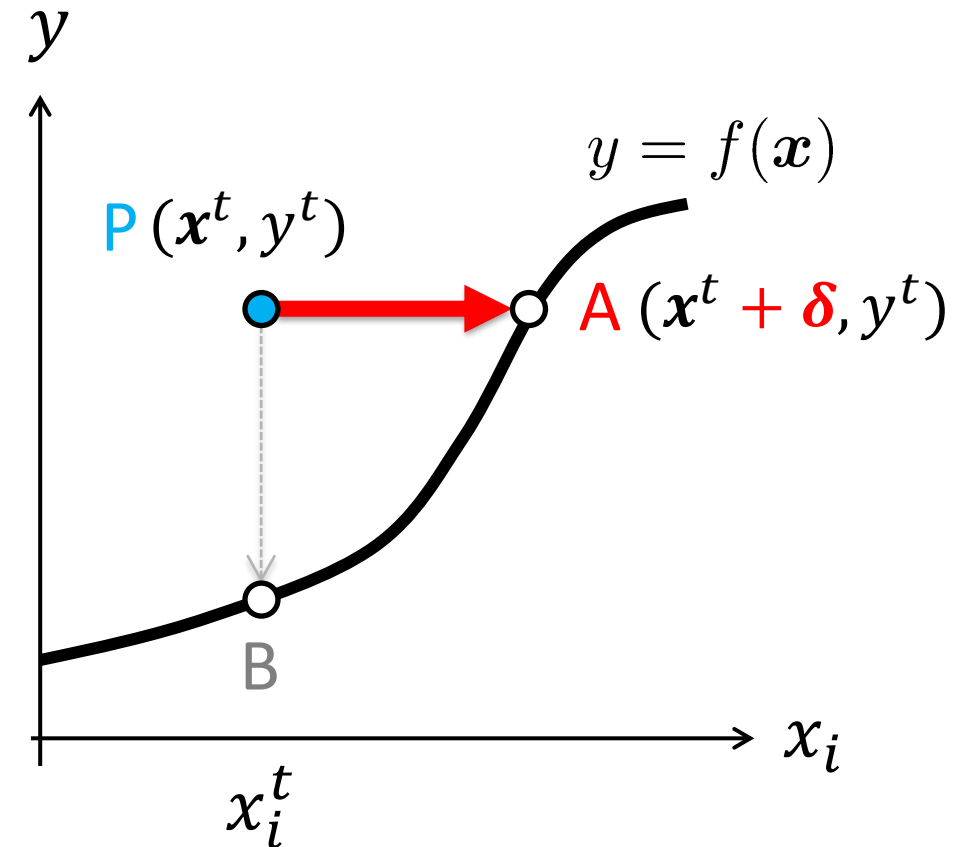


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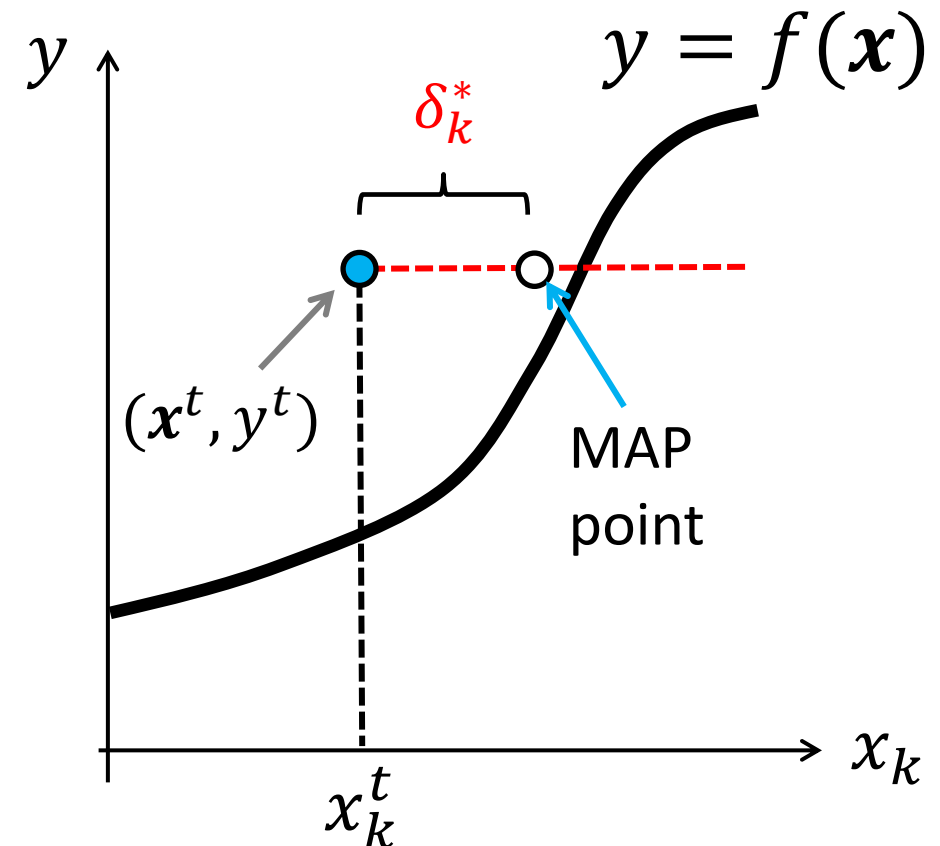
Given a test point (x^t, y^t) being anomalous, we ask:
How much “work” would we need to bring it to the normalcy?

- The “work” required for each variable should be a natural attribution score.
- The outlier **P** wouldn't have been anomalous if it were at **A**.
- Hence, the amount of shift, δ , can be viewed as the “work,” indicating the responsibility of each variable.
- How about B? We need a help of $p(y | x)$.



Perturbation as explanation: Likelihood compensation (LC) [Ide+ 21]

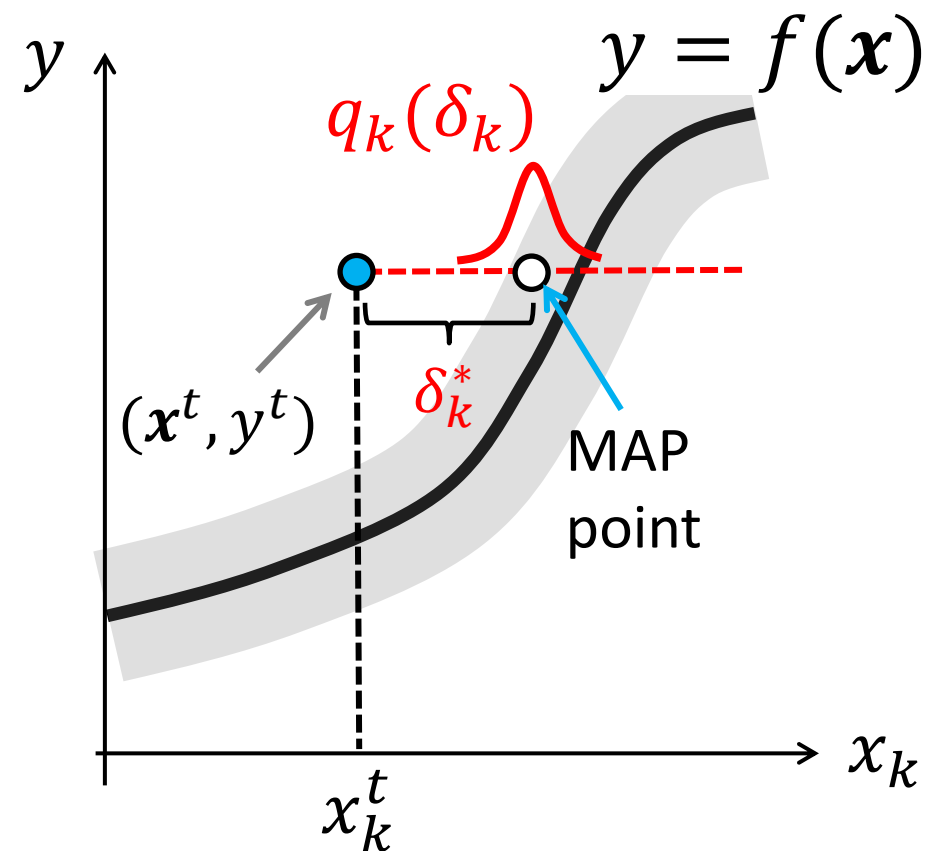
- We need a generative model to handle the ambiguity in prediction.
 - The on-the-curve points may not represent normalcy.
- Generative process with δ as model parameter.
 - observation: $p(y | \mathbf{x}, \delta, \lambda) = \mathcal{N}(y | f(\mathbf{x} + \delta), \lambda^{-1})$
 - prior: $p(\delta) = \mathcal{N}(\delta | \mathbf{0}, \eta \mathbf{I})$
- δ can be determined by solving
 - $\delta^* = \operatorname{argmax}_{\delta} \frac{1}{N_{\text{test}}} \sum_{t=1}^{N_{\text{test}}} \ln p(y^t | x^t, \delta, \lambda) p(\delta)$
 - ✓ Typically, $N_{\text{test}} = 1$



Generative perturbation analysis (GPA) [Ide-Abe 23]: Extending LC to incorporate uncertainty quantification

- The generative process can be viewed as a Bayesian inference model for δ .
 - $p(y | \mathbf{x}, \delta, \lambda) = \mathcal{N}(y | f(\mathbf{x} + \delta), \lambda^{-1})$
 - priors (η, a_0, b_0 are hyperparameters):
 - ✓ $p(\delta) = \mathcal{N}(\delta | \mathbf{0}, \eta \mathbf{I})$
 - ✓ $p(\lambda) = \text{Gam}(\lambda | a_0, b_0)$
- Then, the Bayesian posterior can be viewed as a probabilistic version of LC.
 - Posterior distribution

$$Q(\delta) \propto p(\delta) \prod_{t=1}^{N_{\text{test}}} \int_0^{\infty} d\lambda p(y^t | \mathbf{x}^t, \delta, \lambda) p(\lambda)$$



Separating the contribution of each variable needs variational approximation

- Formal solution of the posterior (typically $N_{\text{test}} = 1$)

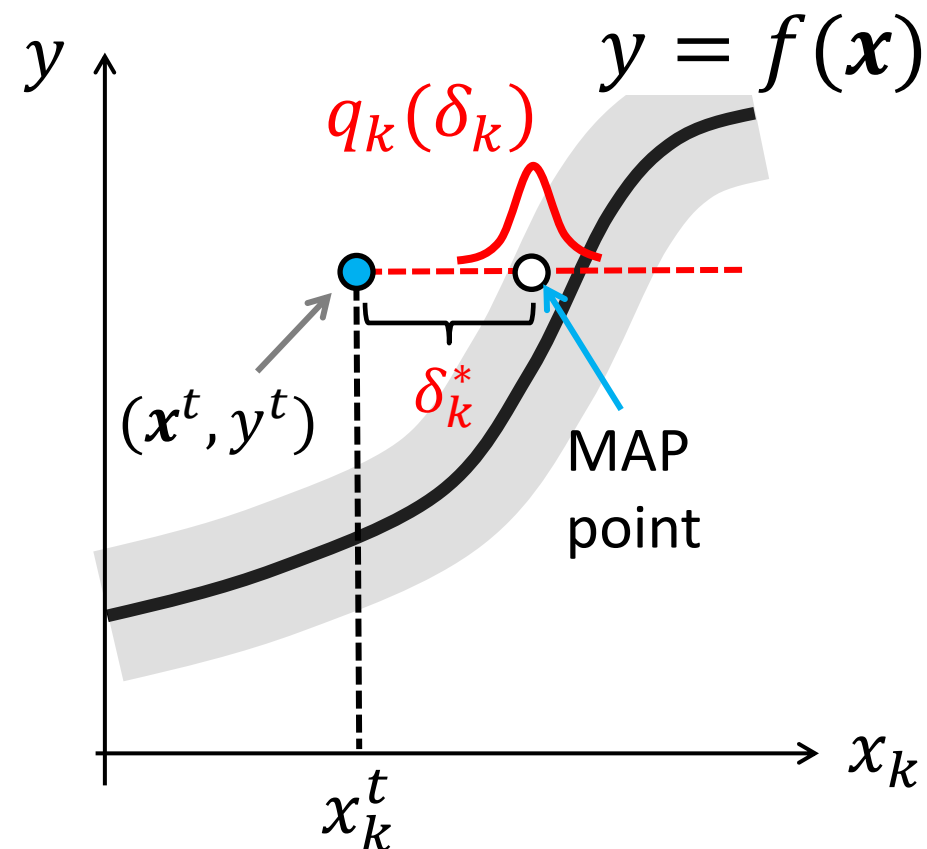
$$Q(\boldsymbol{\delta}) \propto p(\boldsymbol{\delta}) \prod_{t=1}^{N_{\text{test}}} \int_0^\infty d\lambda p(y^t | \mathbf{x}^t, \boldsymbol{\delta}, \lambda) p(\lambda),$$
$$\propto p(\boldsymbol{\delta}) \prod_{t=1}^{N_{\text{test}}} \frac{1}{\sqrt{b_0}} \left\{ 1 + \frac{[y^t - f(\mathbf{x}^t + \boldsymbol{\delta})]^2}{2b_0} \right\}^{-(a_0 + \frac{1}{2})},$$

- How do we get a variable-wise distribution?

- We find an approximated solution by minimizing the KL divergence between $Q(\boldsymbol{\delta})$ and a factorized form:

$$Q(\boldsymbol{\delta}) = Q(\delta_1, \dots, \delta_M) \approx \prod_{k=1}^M q_k(\delta_k),$$

- We also use a mean-field-like approximation to get an explicit form of $\{q_k(\delta_k)\}$. → paper



(For ref.) How the GPA algorithm works

- GPA algorithm has two parts:
 - MAP (maximum a posteriori) estimation
 - Distribution estimation
- MAP estimation solves:

$$\min_{\delta} \left\{ \frac{\eta}{2} \|\delta\|_2^2 + \ln \left\{ 1 + \frac{[y^t - f(\mathbf{x}^t + \delta)]^2}{2b(\mathbf{x}^t)} \right\}^{\frac{2a_0+1}{2}} \right\}$$
 - Use proximal gradient (with ℓ_1 regularizer)
 - The gradient is estimated via local sampling (like LIME)
- Distribution estimation uses a mean-field approximation
 - “Think of the others fixed to the MAP value and focus on yourself.”

Algorithm 2 Generative Perturbation Analysis

Require: $f(x)$, $\mathcal{D}_{\text{test}}$, parameters $\eta, \nu, \kappa, a_0, \{b(\mathbf{x}^t)\}$.

1: randomly initialize $\delta \approx \mathbf{0}$.

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2: repeat MAP
3:   set  $\mathbf{g} = \mathbf{0}$ 
4:   for all  $(y^t, \mathbf{x}^t) \in \mathcal{D}_{\text{test}}$  do
5:     Compute the local gradient  $\frac{\partial f(\mathbf{x}^t + \delta)}{\partial \delta}$ 
6:     Update  $\mathbf{g} \leftarrow \mathbf{g} + \frac{\partial f(\mathbf{x}^t + \delta)}{\partial \delta} \frac{y^t - f(\mathbf{x}^t + \delta)}{2b(\mathbf{x}^t) + [y^t - f(\mathbf{x}^t + \delta)]^2}$ 
7:   end for
8:    $\mathbf{g} \leftarrow (1 - \kappa\eta)\delta + \kappa(2a_0 + 1)\mathbf{g}$ 
9:    $\delta = \text{sign}(\mathbf{g}) \max\{0, |\mathbf{g}| - \eta\nu\}$ 
10: until convergence

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11: set $\delta^* = \delta$

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12: for all  $k$  do distribution
13:    $q_k(\delta) = Q(\delta_1^*, \dots, \delta_{k-1}^*, \delta, \delta_{k+1}^*, \dots, \delta_M^*)$ 
14:    $q_k(\cdot) \leftarrow q_k(\cdot) / \int d\delta' q_k(\delta')$  with Eq. (18)
15: end for

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16: **return** $\{q_k(\cdot) \mid k = 1, \dots, M\}$ and δ^*

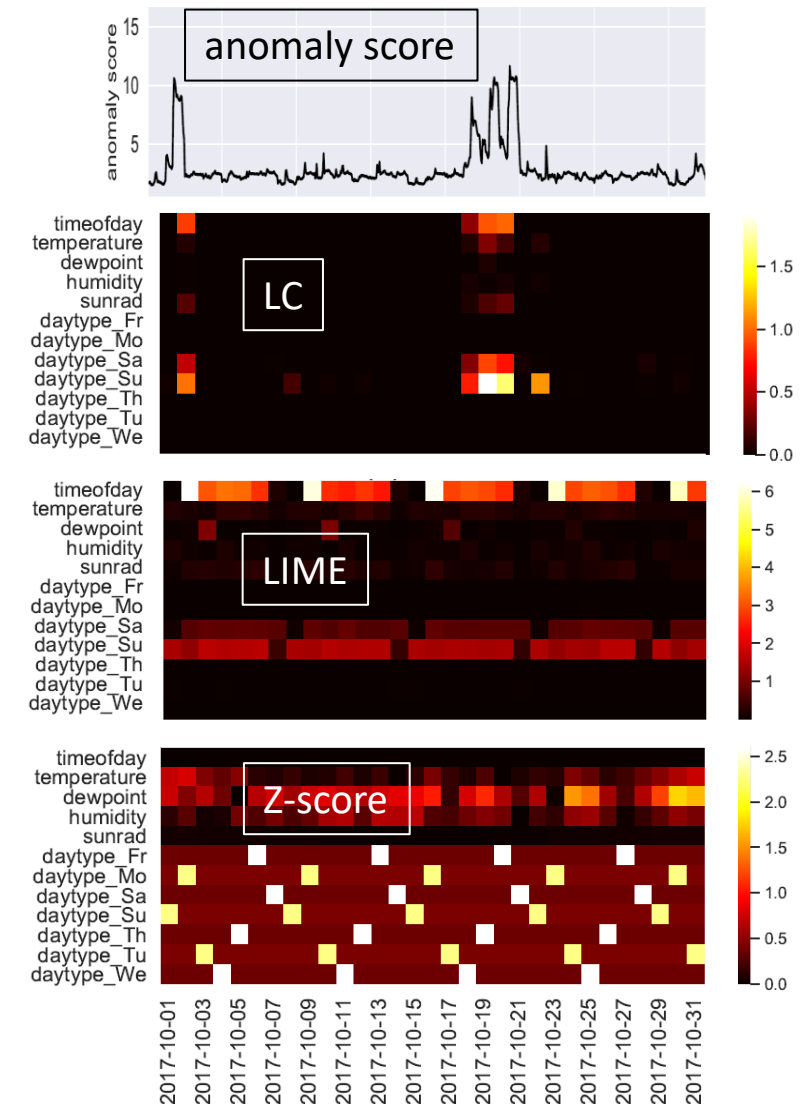
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“Why did they exhibit anomalous energy consumption?”

Building energy use-case

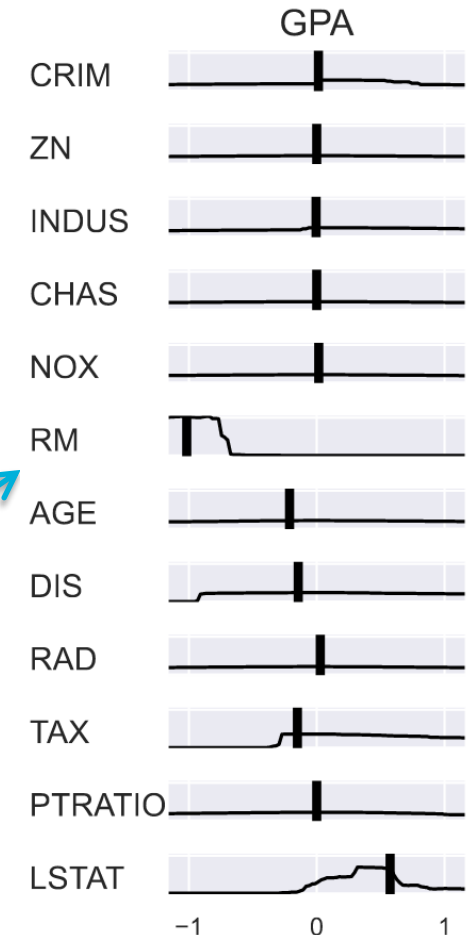
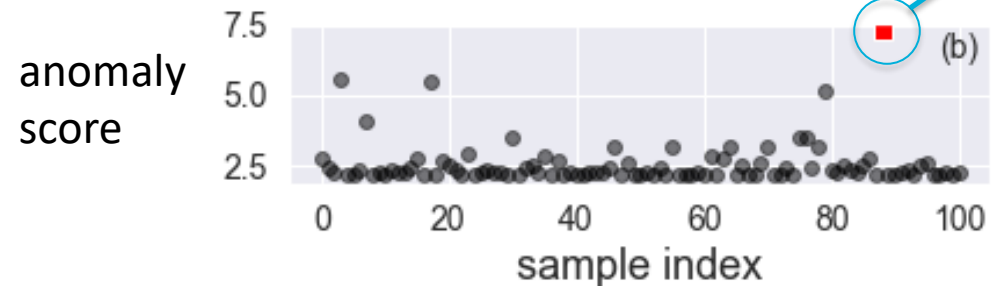
- One month-worth building energy data
 - y : energy consumption
 - x : time of day, temperature, humidity, sun radiation, day of week (one-hot encoded)
- The score is computed based on hourly 24 test points for each day
 - The mean of the absolute values are visualized
- LC pinpoints the root cause: The big scores on daytime_Su and daytime_Sa imply they look like holidays, which is indeed correct!
- LIME is insensitive to outliers
- Z-score does not depend on y (by definition)
 - The artifact for the day-of-week variables is due to one-hot encoding



“Why does this house look so unusual?”

House hunting use-case

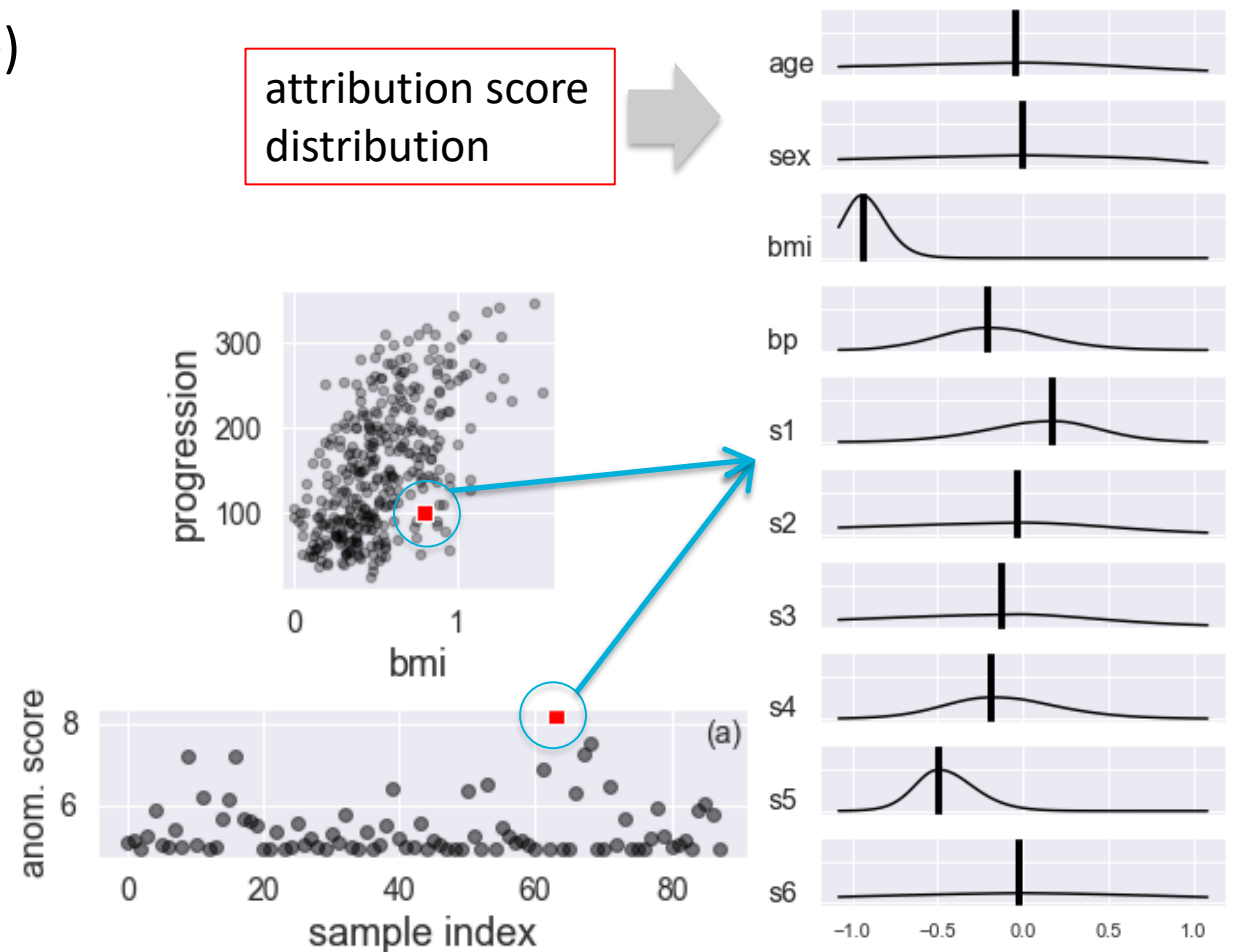
- Boston Housing data
 - y : house price
 - x : house age, # rooms, neighborhood crime rate, etc.
- Computed attribution scores for the top outlier.
 - GPA was able to provide variable-specific distributions
- Is it a bargain? Probably yes.
 - It's got unusually larger #rooms (RM) and lower poor neighbors (LSTAT) than the peers in the same price range.



“Why does this patient look so unusual?”

Healthcare use-case

- Diabetes data
 - y : diabetes' progression (numerical score)
 - x : biomarkers (BMI, blood pressure, etc.)
- Computed attribution score for the top outlier (patient # 63).
 - Found a large negative score in BMI
 - ✓ The high and narrow pdf translates to high confidence
 - For his progression level, he would look like a regular patient if BMI were much smaller:
 - ✓ “He is overweight but healthy (low progression)” or “He is healthy despite overweight”



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Summary

- Introduced the task of black-box anomaly attribution.
- Rather surprisingly, existing major black-box attribution methods are not capable of explaining deviations.
- Introduced the new notion of likelihood compensation (LC, [Ide+ 21]) and its probabilistic extension (GPA, [Ide-Abe 23]).

Thank you!